

Higher-Order Model Checking and its Similarity (?) with SAT Problem

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Self Introduction

- ◆ Working on theory & practice for automated program verification

Automated program verification tools
for functional/imperative/concurrent programs
based on higher-order model checking and
type systems

CHC (a.k.a. CLP) solvers

SMT solvers

SAT solvers

Outline

- ◆ **A brief introduction to higher-order model checking (HOMC)**
 - **What is HOMC?**
 - **Applications**
- ◆ **Why HOMC works in practice?**
 - **similarity/difference with SAT**

Two Notions of Higher-Order Model Checking

	Models	Logic
finite state model checking	finite state systems	modal μ-calculus

Two Notions of Higher-Order Model Checking

	Models	Logic
finite state model checking	finite state systems	modal μ -calculus
HORS model checking [Knapik+ 01; Ong 06]	higher-order recursion schemes (HORS)	modal μ -calculus

A higher-order tree grammar,
useful for modeling a certain class of
infinite state systems
(such as higher-order functional programs)

Two Notions of Higher-Order Model Checking

	Models	Logic
finite state model checking	finite state systems	modal μ -calculus
HORS model checking [Knapik+ 01; Ong 06]	higher-order recursion schemes (HORS)	modal μ -calculus
HFL model checking [Viswanathan & Viswanathan 04]	finite state systems	higher-order modal fixpoint logic (HFL)

Useful for describing non-regular properties

Two Notions of Higher-Order Model Checking

	Models	Logic
finite state model checking	finite state systems	modal μ -calculus
HORS model checking [Knapik+ 01; Ong 06]	higher-order recursion schemes (HORS)	modal μ-calculus (or tree automata)
HFL model checking [Viswanathan & Viswanathan 04]	finite state systems	higher-order modal fixpoint logic (HFL)


Higher-Order Recursion Scheme (HORS)


◆ Grammar for generating an infinite tree

**Order-0 HORS
(regular tree grammar)**

$S \rightarrow a \ c \ B$

$B \rightarrow b \ S$

$S \rightarrow a$

 $c \ B$

$B \rightarrow b$

 S

Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

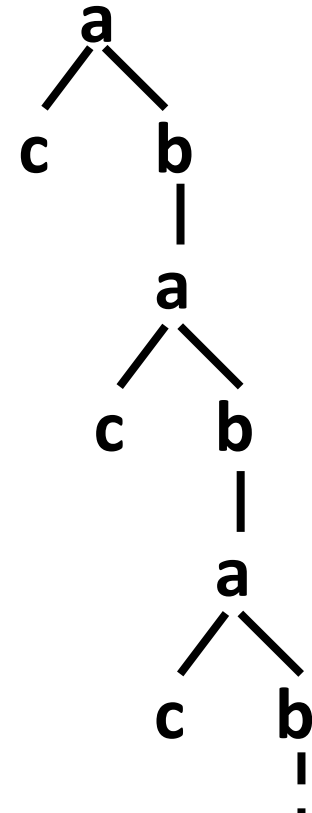
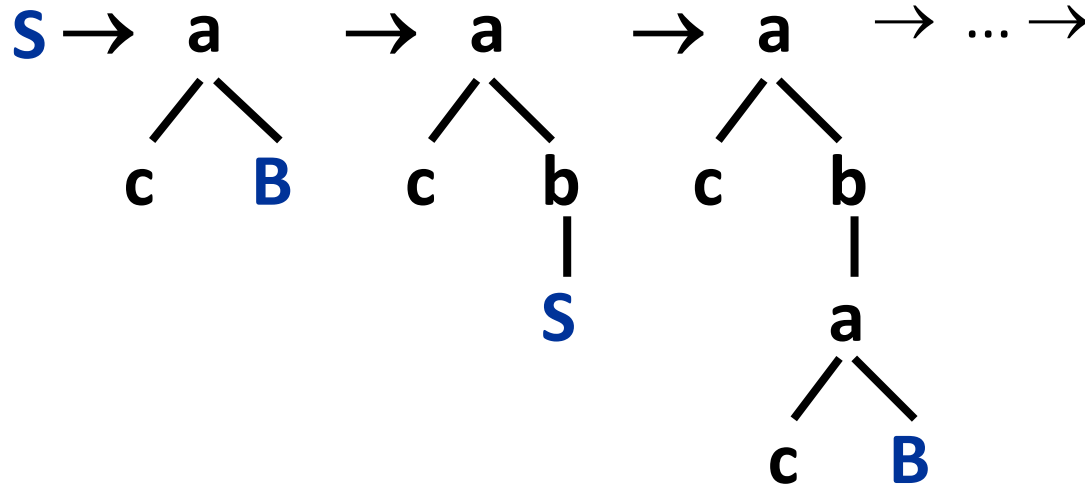
Order-0 HORS
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$S \rightarrow a \ c \ B$

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$S \rightarrow a$
 $\swarrow \searrow$
 $c \ B$

$B \rightarrow b$
 $|$
 S



Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

Order-1 HORS

$$S \rightarrow A c$$
$$A x \rightarrow a x (A (b x))$$
$$S: o, A: o \rightarrow o$$

Notable restriction (compared with ordinary functional programs):

- Rules must be simply-typed.
- There are no pattern matching on trees.

Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

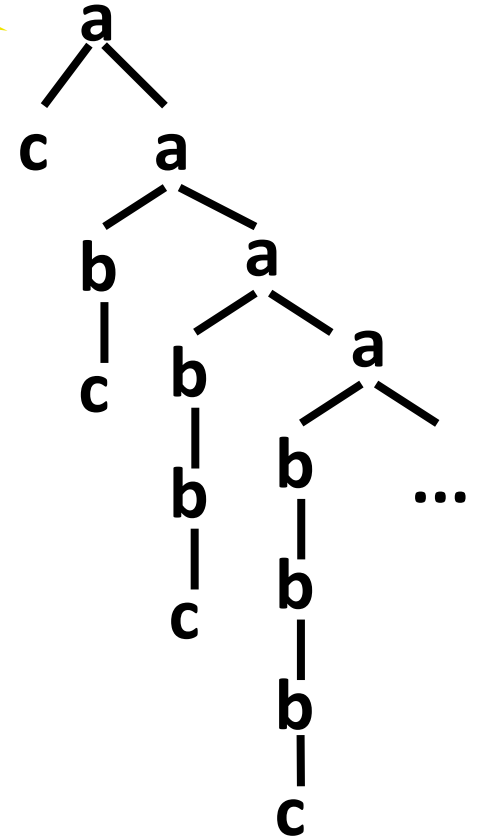
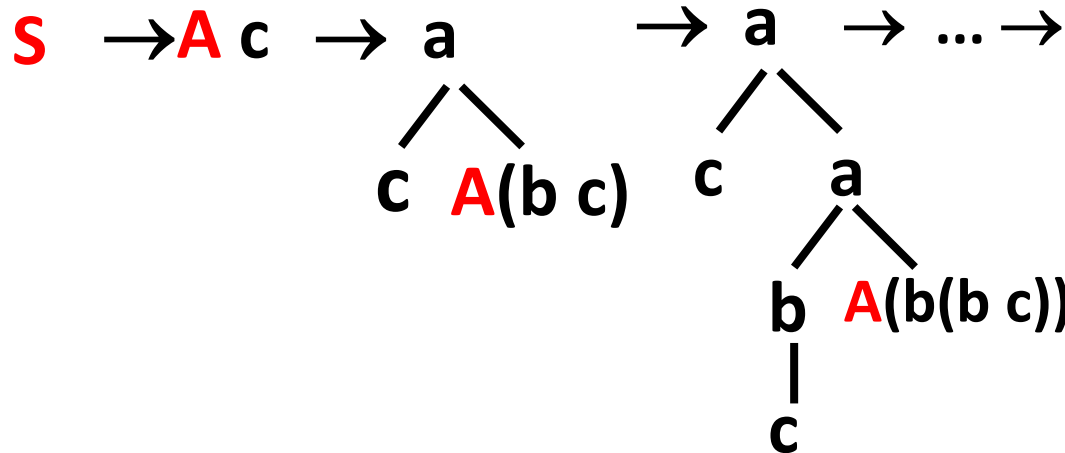
Tree whose paths are labeled by $a^{m+1} b^m c$

Order-1 HORS

$S \rightarrow A c$

$A x \rightarrow a x (A (b x))$

$S: o, A: o \rightarrow o$



Higher-Order Recursion Scheme (HORS)

◆ Grammar for generating an infinite tree

Order-1 HORS

$$S \rightarrow A c$$
$$A x \rightarrow a x (A (b x))$$

S: o, A: o → o

HORS

≈

**A simply-typed functional program
for generating a tree**

HORS Model Checking

Given

G: HORS

**φ : a formula of modal μ -calculus
(or a tree automaton),**

does $\text{Tree}(G)$ satisfy φ ?

e.g.

- Does every finite path end with “c”?**
- Does “a” occur below “b”?**

HORS Model Checking

Order-1 HORS

$S \rightarrow A c$

$A x \rightarrow a x (A (b x))$

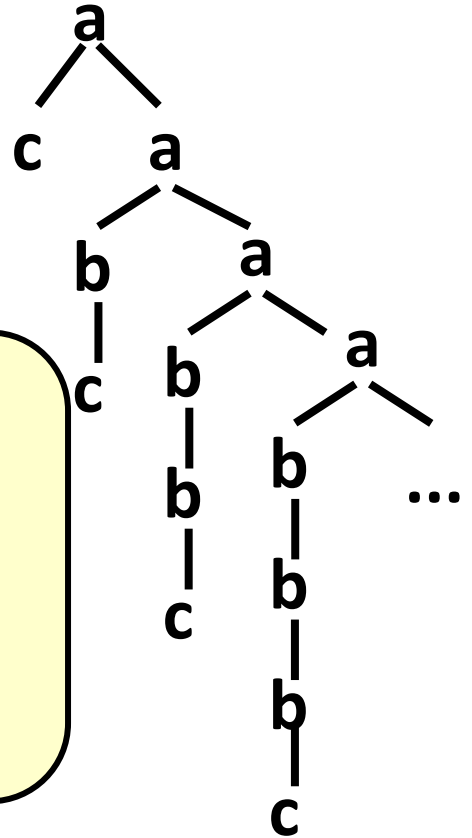
$S: o, A: o \rightarrow o$

Q1. Does every finite path end with "c"?

YES!

Q2. Does "a" occur below "b"?

NO!



HORS Model Checking

Given

G: HORS

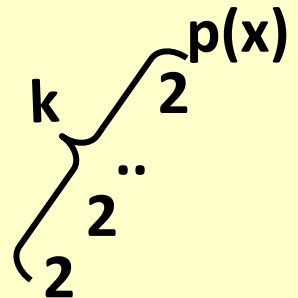
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does $\text{Tree}(\mathbf{G})$ satisfy φ ?

e.g.

- Does every finite path end with “c”?
- Does “a” occur below “b”?

k-EXPTIME-complete [Ong, LICS06]
(for order-k HORS)



TRecS [K. PPDP09]

<http://www-kb.is.s.u-tokyo.ac.jp/~koba/trecs/>

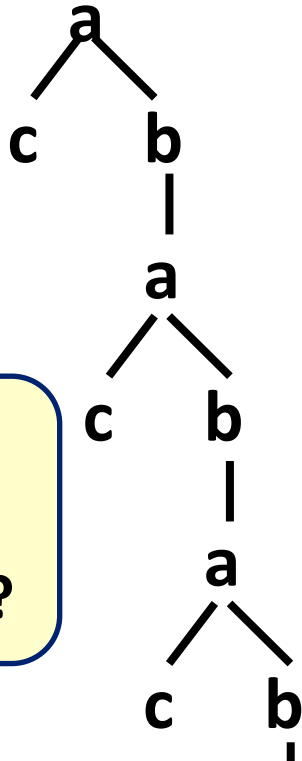


- ◆ The first **practical** model checker for HORS
- ◆ Does not immediately suffer from k-EXPTIME bottleneck
- ◆ A more recent model checker (HorSat2) can scale up to HORS consisting of 100,000 rules, depending on input

HORS Model Checking as Generalization of Finite State/Pushdown Model Checking

- ◆ order-0 \approx finite state model checking
- ◆ order-1 \approx pushdown model checking

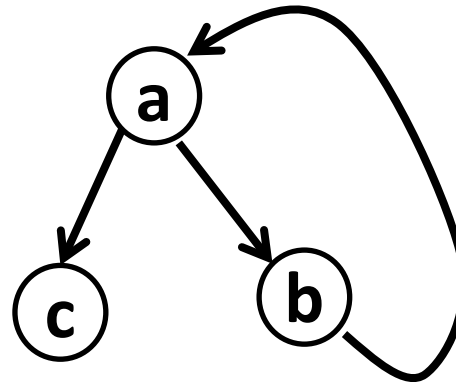
infinite tree



Does “a” occur below “b”?

\approx

transition system

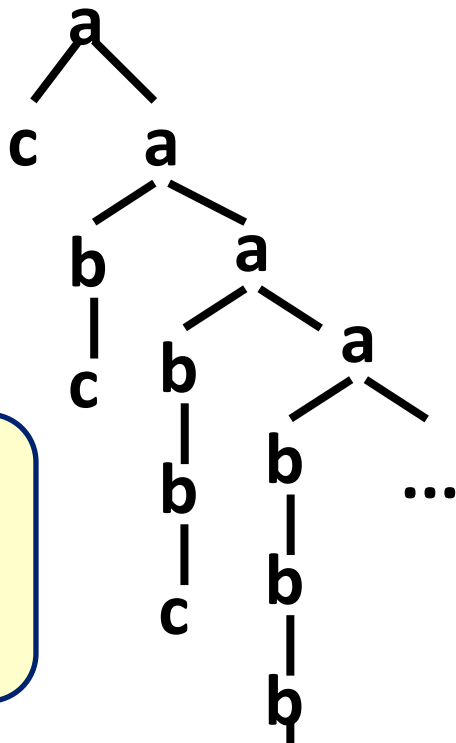


Is there a transition sequence in which “a” occurs after “b”?

HORS Model Checking as Generalization of Finite State/Pushdown Model Checking

- ◆ order-0 \approx finite state model checking
- ◆ order-1 \approx pushdown model checking

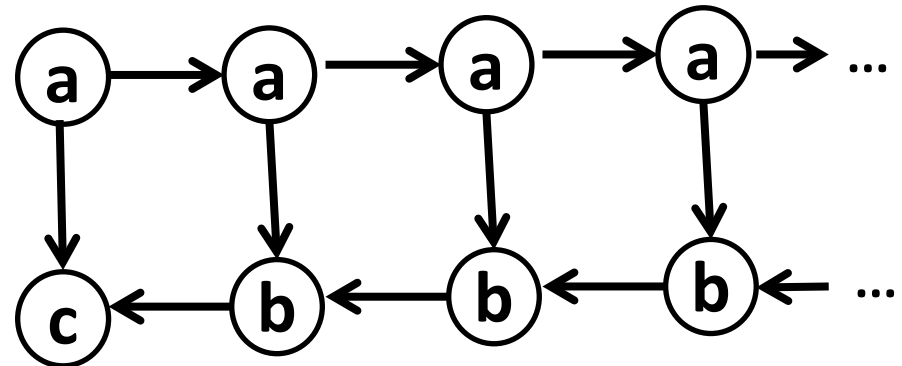
infinite tree



Does "a" occur below "b"?

\approx

(infinite-state) transition system



Is there a transition sequence in which "a" occurs after "b"?

Encoding QBF

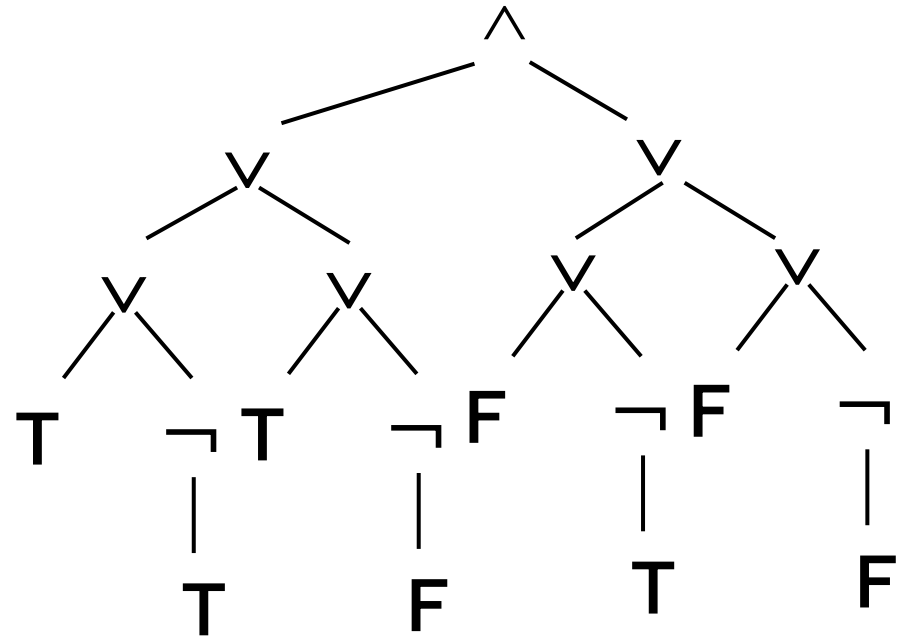
QBF: $\forall x. \exists y. (x \vee \neg y)$

HORS:

S = Forall ($\lambda x. \text{Exists } \lambda y. \vee x (\neg y)$)

Forall f = $\wedge (f \text{ T}) (f \text{ F})$

Exists f = $\vee (f \text{ T}) (f \text{ F})$



Encoding QBF

QBF: $\varphi := \forall x. \exists y. (x \vee \neg y)$

HORS G:

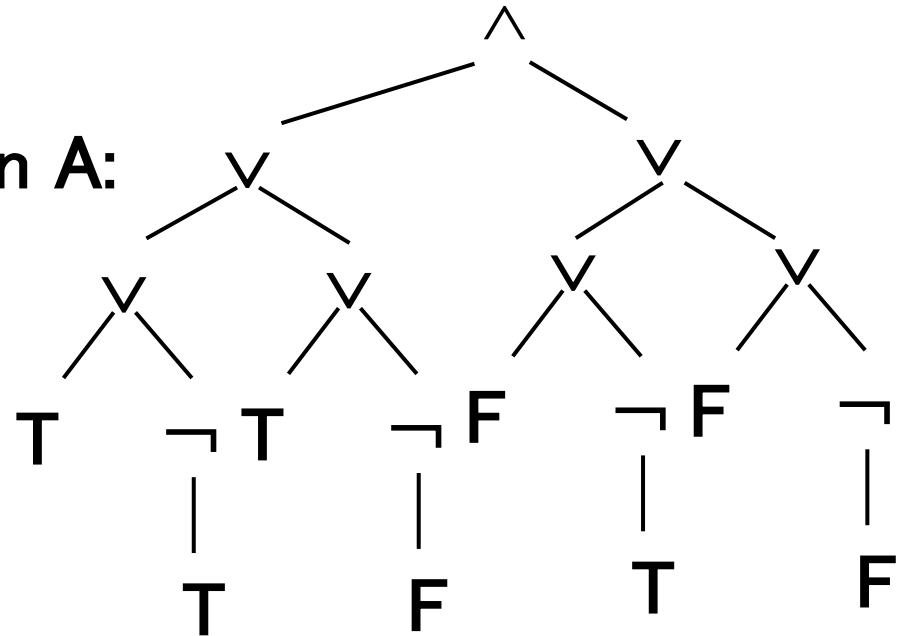
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(Bottom-up) tree automaton A:

$\wedge \text{ T T} \rightarrow \text{T}$	$\vee \text{ F F} \rightarrow \text{F}$
$\wedge _ \text{ F} \rightarrow \text{F}$	$\vee _ \text{ T} \rightarrow \text{T}$
$\wedge \text{ F } _ \rightarrow \text{F}$	$\vee \text{ T } _ \rightarrow \text{T}$
$\neg \text{ T} \rightarrow \text{F}$	$\neg \text{ F} \rightarrow \text{T}$



(with final state: T)

φ is true \Leftrightarrow A accepts Tree(G)

Encoding QBF

QBF: $\varphi := \forall x. \exists y. (x \vee \neg y)$

HORS G:

S = Forall ($\lambda x. \text{Exists } \lambda y. \vee x (\neg y)$)

Forall f = $\wedge (f \text{ T}) (f \text{ F})$

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(Bottom-up) tree automaton A:

$\wedge \text{ T T} \rightarrow \text{T}$ $\vee \text{ F F} \rightarrow \text{F}$

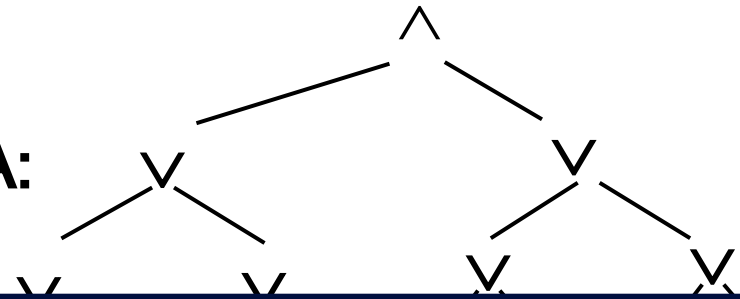
$\wedge _ \text{ F} \rightarrow \text{F}$ $\vee _ \text{ T} \rightarrow \text{T}$

$\wedge \text{ F } _ \rightarrow \text{F}$ $\vee \text{ T } _ \rightarrow \text{T}$

$\neg \text{ T} \rightarrow \text{F}$ $\neg \text{ F} \rightarrow \text{T}$

(with final state: T)

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Remarks:

- HOMC for recursion-free order-1 HORS is PSPACE-complete
- May be useful when a formula is large but can be compactly represented by HORS

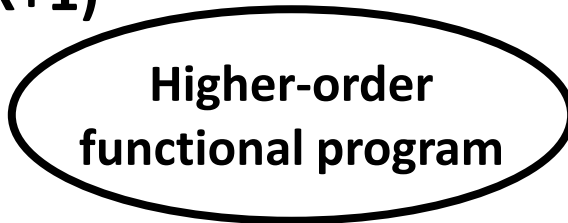
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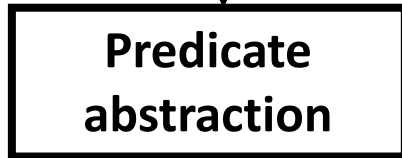
Predicate Abstraction and CEGAR for HORS Model Checking

[K.&Sato&Unno, PLDI2011]

$f(g,x)=g(x+1)$



$\lambda x.x>0$



$f(g, b)=$
if b then $g(\text{true})$
else $g(*)$



Program is unsafe!

Real error path?

yes

Error path

property not satisfied

HORS

model checking

property satisfied

Program is safe!

Tool demonstration:

MoChi

[K&Sato&Unno, 2011]

<https://www.kb.is.s.u-Tokyo.ac.jp/~Ryosuke/mochi/>

**(a software model checker
for a subset of functional programming
language OCaml)**

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Why HORS Model Checking Works (despite k -EXPTIME completeness)

- ◆ Fixed-parameter tractable (FPT) in the size of G
(fixed parameters: the largest size of types,
the size of formulas)
- ◆ Given a “certificate” (intersection types),
the validity of the certificate (for both yes/no
answers) can be efficiently checked.
(cf. NP problem)
 - Hypothesis: Many HO model checking problems
(obtained from program verification problems)
tend to have small certificates

Empirical Evidence for "Small Certificate" Hypothesis?

	order	rules	states	#cert.	$ \Gamma_{\max} $
Twofiles	4	11	5	37	$>10^{10^49}$
TwofilesE	4	12	5	42	$>10^{10^49}$
FileOcamlC	4	23	4	41	$>10^{10^20}$
Lock	4	11	4	41	$>10^{10^20}$
Order5	5	9	5	43	$>10^{10^48}$
mc91	4	49	1	115	$>10^{10^80}$
xhtml	2	64	50	101	$>10^{753}$
exp4-5-3	4	12	3	137	$>10^{10^7}$

#cert: the number of type bindings
in the certificate found by a model checker

Why HORS Model Checking Works (despite k -EXPTIME completeness)

- ◆ Fixed-parameter tractable (FPT) in the size of G
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the size of formulas)
- ◆ Given a “certificate” (intersection types),
the validity of the certificate (for both yes/no
answers) can be efficiently checked.
(cf. NP problem)
- ◆ High complexity is due to the expressive power of
HORS (a finite state system of k -EXP(n) states can be
represented in $O(n)$ -size grammar)

HORS describing a finite-state system with $k\text{-EXP}(m)$ states

Order- n HORS $R_{m,k}$

$S \rightarrow F_0 G_{k-1} \dots G_2 G_1 G_0$

$F_0 f \rightarrow F_1 (F_1 f)$

...

$F_{m-1} f \rightarrow F_m (F_m f)$

$F_m f \rightarrow G_n f$

$G_k f z \rightarrow f (f z)$

...

$G_2 f z \rightarrow f (f z)$

$G_1 z \rightarrow a z$

$G_0 \rightarrow c$

$S \xrightarrow{*} a \quad (G_0)$

$k\text{-EXPTIME}$ algorithm for
order- k HORS

\approx

Polynomial time algorithm for
finite state model checking

HORS describing a finite-state system with $k\text{-EXP}(m)$ states

Order- n HORS $R_{m,k}$

$S \rightarrow F_0 G_{k-1} \dots G_2 G_1 G_0$

$F_0 f \rightarrow F_1 (F_1 f)$

...

$F_{m-1} f \rightarrow F_m (F_m f)$

$F_m f \rightarrow G_n f$

$G_k f z \rightarrow f (f z)$

...

$G_2 f z \rightarrow f (f z)$

$G_1 z \rightarrow a z$

$G_0 \rightarrow c$

$S \xrightarrow{*} a \quad (G_0)$

fixed-parameter polynomial
time algorithm for order- k
HORS

>

Polynomial time algorithm for
finite state model checking

Conclusion

- ◆ **HOMC subsumes many decision problems at low-order**
 - Finite state model checking
 - Pushdown model checking
 - SAT/QBF solving
- ◆ **Applications to higher-order program verification**
- ◆ **HOMC works despite extremely high complexity**
 - … as long as there are small certificates
- ◆ **More efficient HOMC solver using SAT technology?**